

TRANSFER OF LOADS FROM A FINITE NUMBER OF ELASTIC
OVERLAYS WITH FINITE LENGTHS TO AN ELASTIC STRIP
THROUGH ADHESIVE SHEAR LAYERS

A. V. KEROPYAN *

Chair of Mechanics YSU, Armenia

This article deals with the problem of an elastic infinite strip, which is strengthened along its free boundary by a finite number of finite overlays with different elastic characteristics and small constant thicknesses. The interaction between the strip and the overlays is mediated by adhesive shear layers. The overlays are deformed under the action of horizontal forces. The problem of determination of unknown stresses acting between the strip and overlays are reduced to a system of Fredholm integral equations of the second kind for a finite number of unknown functions defined on different finite intervals. It is shown that in the certain domain of variation of the characteristic parameter of the problem this system of integral equations in Banach space may be solved by the method of successive approximations. Particular cases are discussed and the character and behaviour of unknown shear stresses are investigated.

MSC2010: 74M15.

Keywords: contact, overlays (stringers), elastic infinite strip, adhesive shear layer, system of integral equations, operator equation.

Introduction. In [1,2] we considered the transfer of loads from a finite number of finite elastic overlays (stringers) to an elastic half-plane through adhesive layers. Still earlier, in [3,4] we considered a similar problem in the case of two finite elastic overlays for both the elastic half-plane and the infinite strip. The article [5] addresses the problem for an infinite plate (sheet) with two finite stringers, when only one of the stringers is connected through an adhesive layer. Also recall the papers [6–9], where different approaches were used to study similar problems for different elastic bodies, which are strengthened by a single finite stringer through an adhesive layer.

In this article we are going to consider the problem for an elastic infinite strip that is strengthened at finite intervals of its free boundary by an arbitrary finite number of finite overlays with different elastic moduli and small constant thicknesses.

* E-mail: agas50@ysu.am

Statement of the Problem and Obtaining the System of Integral Equations. Let an elastic infinite strip (plane deformation, with Young's modulus E , Poisson's ratio ν and thickness H) be rigidly attached to non-deformable foundation at its boundary $y = -H$ and strengthened along its free boundary $y = 0$ at the finite $[a_j, b_j]$ ($b_j > a_j$, $b_j < a_{j+1}$) intervals by a finite number of finite overlays (stringers) of small constant thicknesses h_j ($h_j \ll b_j - a_j$) and with elastic moduli E_j (hereinafter, the index j takes values in the range 1 to n , unless otherwise stated). The interaction between the strip and the overlays is mediated by thin uniform elastic adhesive layers with Young's modulus E_k , Poisson's ratio ν_k and small constant thickness h_k . The problem is to determine the distribution law of unknown stresses acting between the strip and the overlays, when concentrated forces P_j , are applied at one end points of overlays $x = b_j$, and directed along the Ox axis (see Figure).

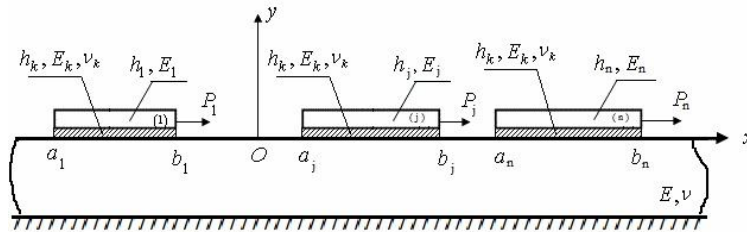


Figure.

The model of uniaxial strain state and the conditions of pure shear are assumed for the overlays (stringers) [10] and the adhesive layers [6], respectively. It is also assumed that only shear (tangential) stresses act between the strip and the overlays [1–9].

With such assumptions, let write the horizontal displacements $u(x, 0)$ of the boundary points of the elastic strip in the form [3]:

$$u(x, 0) = \sum_{i=1}^n \int_{a_i}^{b_i} K(|x-s|) \tau_i(s) ds, \quad (1)$$

when on the $[a_j, b_j]$ segments of its free $y = 0$ boundary there act shear (tangential) forces with intensities $\tau_j(x)$, respectively. In Eq. (1)

$$K(|x|) = \frac{1}{2\pi} \int_{-\infty}^{\infty} K_n(\sigma) e^{-i\sigma x} d\sigma, \quad (2)$$

$$K_n(\sigma) = \frac{(2\chi + 1)[(\chi + 1) \sinh 2H|\sigma| + 2\chi H|\sigma|]}{2\mu|\sigma|[2\chi(\chi + 1) \cosh 2H\sigma + \chi^2(4H^2\sigma^2 + 1) + (\chi + 1)^2]},$$

$$\chi = \frac{\lambda + \mu}{2\mu},$$

λ, μ are Lamé's constants of elasticity of the material of the strip.

Now, assuming that each differential element of the adhesive layers is in a condition of pure shear [1–9], the following conditions are obtained:

$$u^{(j)}(x) - u(x, 0) = k\tau_j(x), \quad a_j \leq x \leq b_j, \quad j = \overline{1, n}, \quad (3)$$

where $k = h_k/G_k$, $G_k = E_k/2(1 + \nu_k)$, $\tau_j(x) = G_k\gamma_k^{(j)}(x)$. G_k is the shear modulus of the adhesive layers, $u^{(j)}(x)$ are the horizontal displacements of the points of the elastic overlays on the $[a_j, b_j]$ intervals, $\tau_j(x)$ and $\gamma_k^{(j)}(x)$ are the shear stresses and the shear strains in the adhesive layers on the $[a_j, b_j]$ intervals, respectively.

Further, taking into account the above assumptions [1–10], the equilibrium differential equations for overlays on the $[a_j, b_j]$ finite intervals will be written in the following form:

$$\frac{d^2u^{(j)}}{dx^2} = \frac{\tau_j(x)}{E_j h_j}, \quad a_j \leq x \leq b_j, \quad j = \overline{1, n}, \quad (4)$$

which, by virtue of (3), can be written in the form:

$$\frac{d^2u^{(j)}}{dx^2} - \gamma_j^2 u^{(j)}(x) = -\gamma_j^2 u(x, 0), \quad a_j \leq x \leq b_j, \quad (5)$$

where we have also the following boundary conditions:

$$\left. \frac{du^{(j)}}{dx} \right|_{x=a_j} = 0, \quad \left. \frac{du^{(j)}}{dx} \right|_{x=b_j} = \frac{P_j}{E_j h_j}. \quad (6)$$

Here $\gamma_j^2 = 1/kE_j h_j$, $j = \overline{1, n}$.

The solutions of the boundary value problems (5) and (6) we obtain in the form:

$$u^{(j)}(x) = u_0^{(j)}(x) + \gamma_j^2 \int_{a_j}^{b_j} G_j(x, s) u(s, 0) ds, \quad a_j \leq x \leq b_j, \quad (7)$$

where $u_0^{(j)}(x)$ are the general solutions of the homogenous equations corresponding to Eq. (5) with the boundary conditions (6) and have the form

$$u_0^{(j)}(x) = \frac{P_j \cosh[\gamma_j(x - a_j)]}{\gamma_j E_j h_j \sinh[\gamma_j(b_j - a_j)]},$$

and $G_j(x, s)$ are Green's functions [11]:

$$G_j(x, s) = \frac{1}{\gamma_j \sinh[\gamma_j(b_j - a_j)]} \begin{cases} \cosh \gamma_j(x - b_j) \cosh \gamma_j(s - a_j), & x > s, \\ \cosh \gamma_j(x - a_j) \cosh \gamma_j(s - b_j), & x < s. \end{cases}$$

It is obvious, that the functions $G_j(x, s)$ are continuous in both variables and are symmetric with respect to permutation of variables $G_j(x, s) = G_j(s, x)$.

Further, by virtue of (7), from (3) we obtain the following equations

$$k\tau_j(x) + u(x, 0) = \gamma_j^2 \int_{a_j}^{b_j} G_j(x, s) u(s, 0) ds + u_0^{(j)}(x), \quad a_j \leq x \leq b_j, \quad j = \overline{1, n}. \quad (8)$$

Now, by matching (1) and (8), we get a system of integral equations with respect to unknown shear stresses $\tau_j(x)$, which are specified in different finite $[a_j, b_j]$

intervals, in the form:

$$\begin{aligned} \tau_j(x) + \frac{1}{k} \sum_{i=1}^n \int_{a_i}^{b_i} K(|x-s|) \tau_i(s) ds - \\ - \frac{\gamma_j^2}{k} \sum_{i=1}^n \int_{a_j}^{b_j} G_j(x,s) \left[\int_{a_i}^{b_i} K(|s-t|) \tau_i(t) dt \right] ds = \frac{u_0^{(j)}(x)}{k}, \quad j = \overline{1, n}, \quad (9) \end{aligned}$$

or, changing the order of integration in double integrals, in the form:

$$\begin{aligned} \tau_j(x) + \frac{1}{k} \sum_{i=1}^n \int_{a_i}^{b_i} K(|x-t|) \tau_i(t) dt - \\ - \frac{\gamma_j^2}{k} \sum_{i=1}^n \int_{a_i}^{b_i} \left[\int_{a_j}^{b_j} G_j(x,s) K(|s-t|) ds \right] \tau_i(t) dt = \frac{u_0^{(j)}(x)}{k}. \quad (10) \end{aligned}$$

Further, note that according to (2) the kernel $K(|x|)$ can be represented in the following form:

$$K(|x|) = \frac{A_1}{\pi} \left(\ln \frac{1}{|A_1 x|} - C \right) + \frac{A_1}{\pi} R(x), \quad (11)$$

where $A_1 = \frac{2\chi + 1}{4\chi\mu} = \frac{2(1 - \nu^2)}{E}$ and C is Euler's constant. In (11) $R(x)$ is the regular part of the kernel $K(|x|)$ and has the form

$$\begin{aligned} R(x) = \pi \sum_{n=1}^{\infty} (-1)^n \left[\frac{(A_1 x)^{2n}}{\pi(2n)!} \left(\ln \frac{1}{|A_1 x|} + 1 + \frac{1}{2} + \dots + \frac{1}{2n} - C \right) - \frac{|A_1 x|^{2n-1}}{2(2n-1)!} \right] + \\ + \frac{1}{2A_1} \int_{-\infty}^{\infty} \frac{[(A_1 + |\sigma|)K_n(\sigma) - A_1] e^{-i\sigma x} d\sigma}{A_1 + |\sigma|}, \end{aligned}$$

since

$$K_n(\sigma) \sim A_1 |\sigma|^{-1}, \quad \text{as } |\sigma| \rightarrow \infty. \quad (12)$$

Now, by virtue of (11), we can bring the system (10) to the form:

$$\begin{aligned} \tau_j(x) + \frac{A_1}{\pi k} \sum_{i=1}^n \int_{a_i}^{b_i} \left(\ln \frac{1}{A_1 |x-t|} - C \right) \tau_i(t) dt + \frac{A_1}{\pi k} \sum_{i=1}^n \int_{a_i}^{b_i} R(x-t) \tau_i(t) dt - \\ - \frac{\gamma_j^2 A_1}{\pi k} \sum_{i=1}^n \int_{a_i}^{b_i} \left[\int_{a_j}^{b_j} G_j(x,s) \left(\ln \frac{1}{A_1 |s-t|} - C \right) ds \right] \tau_i(t) dt - \\ - \frac{\gamma_j^2 A_1}{\pi k} \sum_{i=1}^n \int_{a_i}^{b_i} \left[\int_{a_j}^{b_j} G_j(x,s) R(s-t) ds \right] \tau_i(t) dt = \frac{u_0^{(j)}(x)}{k}. \quad (13) \end{aligned}$$

Next, replacing the variables x , s and t by ax , as and at respectively, where $a > 0$ is the coordinate of one of the endpoints of a certain overlay, we obtain the system (13) in the following form:

$$\begin{aligned} \psi_j(x) + \delta^2 \sum_{i=1}^n \int_{\alpha_i}^{\beta_i} \ln \frac{1}{|x-t|} \psi_i(t) dt + \delta^2 \sum_{i=1}^n \int_{\alpha_i}^{\beta_i} R_*(x-t) \psi_i(t) dt - \\ - a\gamma_j^2 \delta^2 \sum_{i=1}^n \int_{\alpha_i}^{\beta_i} \left[\int_{\alpha_j}^{\beta_j} G_j(ax, as) \ln \frac{1}{|s-t|} ds \right] \psi_i(t) dt - \\ - a\gamma_j^2 \delta^2 \sum_{i=1}^n \int_{\alpha_i}^{\beta_i} \left[\int_{\alpha_j}^{\beta_j} G_j(ax, as) R_*(s-t) ds \right] \psi_i(t) dt = \frac{au_0^{(j)}(ax)}{k}. \end{aligned} \quad (14)$$

One can represent the system of integral equations (14) in the following form:

$$\psi_j(x) + \delta^2 \sum_{i=1}^n \int_{\alpha_i}^{\beta_i} L_j(x,t) \psi_i(t) dt = f_0^{(j)}(x), \quad \alpha_j \leq x \leq \beta_j, \quad j = \overline{1, n}, \quad (15)$$

where

$$\begin{aligned} L_j(x,t) = \ln \frac{1}{|x-t|} + R_*(x-t) - \\ - a\gamma_j^2 \int_{\alpha_j}^{\beta_j} G_j(ax, as) \ln \frac{1}{|s-t|} ds - a\gamma_j^2 \int_{\alpha_j}^{\beta_j} G_j(ax, as) R_*(s-t) ds, \quad (16) \\ f_0^{(j)}(x) = \frac{au_0^{(j)}(ax)}{k} = \frac{P_j a \gamma_j \cosh[a\gamma_j(x - \alpha_j)]}{\sinh[a\gamma_j(\beta_j - \alpha_j)]}, \end{aligned}$$

$$\delta^2 = aA_1/\pi k, \quad \alpha_j = a_j/a, \quad \beta_j = b_j/a, \quad \psi_j(x) = a\tau_j(ax), \quad R_*(z) = R(az),$$

$R_*(z)$ is a square integrable function.

Note that the system (10) or (15) has been obtained by the changing the order of integration, the validity of which follows from the Fubini's theorem [11], as well as from the equalities

$$\int_{\alpha_j}^{\beta_j} G_j(ax, as) ds = \frac{1}{a\gamma_j^2}, \quad (17)$$

which, in turn, follow from the equalities [1, 2]:

$$\begin{aligned} \int_{a_j}^{b_j} G_j(x, s) \cos \left[\frac{m\pi(s - a_j)}{b_j - a_j} \right] ds = \\ = \frac{(b_j - a_j)^2}{(b_j - a_j)^2 \gamma_j^2 + m^2 \pi^2} \cos \left[\frac{m\pi(x - a_j)}{b_j - a_j} \right], \quad m = 0, 1, 2, \dots, \end{aligned} \quad (18)$$

where the functions $\cos \left[\frac{m\pi(x-a_j)}{b_j-a_j} \right]$, $m = 0, 1, 2, \dots$, form full orthogonal systems in the spaces $L_2(a_j, b_j)$. Note [11] that the symmetric completely continuous integral operator B :

$$B\varphi = \int_a^b G(x, s)\varphi(s) ds,$$

which acts in the space $L_2(a, b)$, is an inverse of the operator $D = -d^2/dx^2 + \gamma^2 I$.

Below the Fubini's theorem will be used without special mention.

Also note that the system (15) has been obtained without using the equilibrium conditions imposed on the overlays

$$\int_{\alpha_j}^{\beta_j} \psi_j(ax) dx = P_j. \quad (19)$$

In the system (15), the conditions (19) are satisfied automatically due to the following relations

$$\int_{\alpha_j}^{\beta_j} f_0^{(j)}(x) dx = P_j/a.$$

These can be easily verified by integrating the equations (15) from α_j to β_j , then changing the order of integration in resulting double integrals and taking into account the equalities

$$\int_{\alpha_j}^{\beta_j} L_j(x, t) dx = 0,$$

which follow from (18).

Thus, the solution of the problem is reduced to solving the system (15) of Fredholm integral equations of the second kind with kernels squarely integrable in two variables and with right-hand sides which are the solutions of the problem in the case of rigid base.

From the system (15), it is easy to see that at the end points of overlays $x = \alpha_j$ and $x = \beta_j$ the values of unknown shear stresses $\psi_j(x)$ are finite.

Investigation of Solvability of the system of Integral Equations (15). Further, write system (15) in the following form:

$$\varphi + T\varphi = g_0, \quad (20)$$

where

$$\varphi = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \vdots \\ \psi_n \end{pmatrix}, \quad g_0 = \begin{pmatrix} f_0^{(1)} \\ f_0^{(2)} \\ \vdots \\ f_0^{(n)} \end{pmatrix}, \quad T = \begin{pmatrix} \delta^2 k_{11} & \delta^2 k_{12} & \dots & \delta^2 k_{1n} \\ \delta^2 k_{21} & \delta^2 k_{22} & \dots & \delta^2 k_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \delta^2 k_{n1} & \delta^2 k_{n2} & \dots & \delta^2 k_{nn} \end{pmatrix},$$

$$k_{ji}\psi_i = \int_{\alpha_i}^{\beta_i} L_j(x,t)\psi_i(t) dt, \quad j, i = \overline{1, n}. \tag{21}$$

Now consider Eq. (20) in Banach space by dint of vector-functions $X = \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix}$, where $X_j \in L_2(\alpha_j, \beta_j)$, and with the norm:

$$\|X\| = \max \left\{ \|X_1\|_{L_2(\alpha_1, \beta_1)}, \|X_2\|_{L_2(\alpha_2, \beta_2)}, \dots, \|X_n\|_{L_2(\alpha_n, \beta_n)} \right\}.$$

$L_2(\alpha_j, \beta_j)$ are spaces of square integrable functions, specified on the intervals (α_j, β_j) .

Operators k_{ji} , $j, i = \overline{1, n}$, act as follows: $k_{ji} : L_2(\alpha_i, \beta_i) \rightarrow L_2(\alpha_j, \beta_j)$.

Obviously, the operator T acts in the B space and is Fredholm's operator. The operational Eq. (20) in the B space can be solved by the method of successive approximations, if $\|T\| < 1$, where

$$\|T\| = \max \left\{ \delta^2 (\|k_{11}\| + \dots + \|k_{1n}\|), \dots, \delta^2 (\|k_{n1}\| + \dots + \|k_{nn}\|) \right\}.$$

That is, the condition $\|T\| < 1$ will be satisfied, if

$$\delta^2 (\|k_{11}\| + \dots + \|k_{1n}\|) < 1, \quad \delta^2 (\|k_{21}\| + \dots + \|k_{2n}\|) < 1, \dots, \quad \delta^2 (\|k_{n1}\| + \dots + \|k_{nn}\|) < 1. \tag{22}$$

Then the solution of Eq. (20) will be written in the form:

$$\varphi = (I + T)^{-1}g_0 = \sum_{m=0}^{\infty} (-1)^m T^m g_0.$$

Now determine the values of δ^2 parameter, for which the conditions (22) will be satisfied. From (21), by virtue of Cauchy–Bunyakovski inequality, we get:

$$\|k_{ji}\| \leq e_{ji}, \quad e_{ji} = \left(\int_{\alpha_i}^{\beta_i} \int_{\alpha_j}^{\beta_j} L_j^2(x,t) dx dt \right)^{\frac{1}{2}}, \quad j, i = \overline{1, n}. \tag{23}$$

The expressions for e_{ji} , are difficult to calculate, so, we will estimate them. As will be justified below, the following estimates take place:

$$e_{ji} < \frac{l_j}{2} \left(\int_{\alpha_i}^{\beta_i} \int_{\alpha_j}^{\beta_j} \ln^2|x-t| dx dt \right)^{\frac{1}{2}} + \frac{l_j}{2} \left(\int_{\alpha_i}^{\beta_i} \int_{\alpha_j}^{\beta_j} R_*^2(x-t) dx dt \right)^{\frac{1}{2}}, \quad l_j = \beta_j - \alpha_j. \tag{24}$$

First, let us get the estimate (24) in the case of $i = j$. To this end, recall that in the Eq. (18), as mentioned above, the functions $\cos[m\pi(x - \alpha_j)/l_j]$, $m = 0, 1, 2, \dots$, constitute full orthogonal systems in the spaces $L_2(\alpha_j, \beta_j)$. Then, according to Parseval's equality, we have (since $L_{j0} = 0$)

$$\frac{2}{l_j} \int_{\alpha_j}^{\beta_j} L_j^2(x,t) dx = \sum_{m=1}^{\infty} L_{jm}^2(t), \quad \alpha_j < t < \beta_j, \tag{25}$$

where

$$L_{jm}(t) = \int_{\alpha_j}^{\beta_j} L_j(x,t) \cos \left[\frac{m\pi(x-\alpha_j)}{l_j} \right] dx, \quad m = 1, 2, \dots$$

Further, according to (18), we have

$$L_{jm}(t) = \left(1 - \frac{\gamma_1^2 l_j^2}{\gamma_1^2 l_j^2 + m^2 \pi^2} \right) \eta_{jm}(t), \quad m = 1, 2, \dots,$$

where

$$\eta_{jm}(t) = \int_{\alpha_j}^{\beta_j} \left[\ln \frac{1}{|x-t|} + R_*(x-t) \right] \cos \left[\frac{m\pi(x-\alpha_j)}{l_j} \right] dx, \quad m = 1, 2, \dots$$

Therefore,

$$\frac{2}{l_j} \int_{\alpha_j}^{\beta_j} L_j^2(x,t) dx = \sum_{m=1}^{\infty} \left(1 - \frac{\gamma_j^2 l_j^2}{\gamma_j^2 l_j^2 + m^2 \pi^2} \right)^2 \eta_{jm}^2(t) < \sum_{m=1}^{\infty} \eta_{jm}^2(t),$$

$$\alpha_j < t < \beta_j.$$

On the other hand, by virtue Cauchy–Bunyakovski inequality, we obtain

$$\sum_{m=1}^{\infty} \eta_{jm}^2(t) \leq \frac{l_j}{2} \int_{\alpha_j}^{\beta_j} \left[\ln \frac{1}{|x-t|} + R_*(x-t) \right]^2 dx.$$

Finally, applying the Cauchy inequality, we get:

$$e_{jj} < \frac{l_j}{2} \left(\int_{\alpha_j}^{\beta_j} \int_{\alpha_j}^{\beta_j} \ln^2 |x-t| dx dt \right)^{\frac{1}{2}} + \frac{l_j}{2} \left(\int_{\alpha_j}^{\beta_j} \int_{\alpha_j}^{\beta_j} R_*^2(x-t) dx dt \right)^{\frac{1}{2}}.$$

The estimates (24) for e_{ji} , $j \neq i$, one can obtain in a similar way.

Then the conditions (22) will be satisfied if

$$\delta^2 < \left(\sum_{i=1}^n e_{ji} \right)^{-1} = e_j. \quad (26)$$

Therefore, we have obtained the condition of realization of (22) in the form $\delta^2 < \min(e_1, e_2, \dots, e_n)$, where e_j are positive numbers, less than unity.

The values of unknown shear stresses $\psi_j(x)$ at the end points $x = \alpha_j$ and $x = \beta_j$ of overlays one can obtain from system (15).

It may be appropriate to note that comprehensive and deep numerical analysis for the elastic half-plane in cases of $n = 1, 2$ are presented in [1]. Without going into details, note that some still unpublished numerical results of analyzing the system of integral equations (15) with $n = 1, 2$ in some particular cases with the matching values of the characteristic parameters correspond to the calculated results presented in [1] (see Figs. 4, 5 and Fig. 7 in [1]).

Conclusion. To study the changes in the law of distribution of unknown shear stresses depend on the characteristic parameters of the problem, this article presents an effective solution to the problem in question. The problem is reduced to solving a finite system of Fredholm integral equations of the second kind, which can be solved by the method of successive approximations. The solution of the problem in question can also be reduced to solving a finite system of singular integro-differential equations of the second kind with a Cauchy kernel and with certain boundary conditions. Its solutions can be constructed using Chebishev's orthogonal polynomials of second kind using the method given in [3].

A brief account on the presented work has been reported at the IX International Conference on the problem of dynamics of interaction of deformable media [12].

Received 23.10.2018

Reviewed 15.01.2019

Accepted 02.04.2019

REFERENCES

1. Kerobyan A.V., Sahakyan K.P. Loads Transfer from Finite Number Finite Stringers to an Elastic Half-Plane Through Adhesive Shear Layers. *Proceedings of NAS RA. Mechanics*, **70**:3 (2017), 39–56 (in Russian).
2. Kerobyan A.V. *Contact Problem for an Elastic Half-Plane with Finite Number Finite Elastic Overlays in the Presence of Shear Interlayers. Topical Problems of Continuum Mechanics.* Proceedings of IV Inter. Conference. Yer. (2015), 241–245 (in Russian).
3. Kerobyan A.V. Contact Problems for an Elastic Strip and the Infinite Plate with Two Finite Elastic Overlays in the Presence of Shear Interlayers. *Proceedings of NAS RA, Mechanics*, **67**:1 (2014), 22–34 (in Russian).
4. Kerobyan A.V. About Contact Problems for an Elastic Half-Plane and the Infinite Plate with Two Finite Elastic Overlays in the Presence of Shear Interlayers. *Proceedings of the YSU. Physical and Mathematical Sciences*, **2** (2015), 30–38.
5. Grigoryan E.Kh., Kerobyan A.V., Shahinyan S.S. The Contact Problem for the Infinite Plate with Two Finite Stringers One from Which is Glued, Other is Ideal Conducted. *Proceedings of NAS RA. Mechanics*, **55**:2 (2002), 14–23 (in Russian).
6. Lubkin J.L., Lewis L.C. Adhesive Shear Flow for an Axially Loaded, Finite Stringer Bonded to an Infinite Sheet. *Quarterly Journal of Mechanics and Applied Mathematics*, **XXIII** (1970), 521–533.
7. Kerobyan A.V., Sarkisyan V.S. *The Solution of the Problem for an Anisotropic Half-Plane on the Boundary of which Finite Length Stringer is Glued.* Proceedings of the Scientific Conference, Dedicated to the 60th Anniversary of the Pedagogical Institute of Gyumri. Gyumri: Vysshaya Shkola, **1** (1994), 73–76 (in Russian).
8. Grigoryan E.Kh. On Solution of Problem for an Elastic Infinite Plate, One the Surface of which Finite Length Stringer is Glued. *Proceedings of NAS RA. Mechanics*, **53**:4 (2000), 11–16 (in Russian).
9. Sarkisyan V.S., Kerobyan A.V. On the Solution of the Problem for Anisotropic Half-Plane on the Edge of which a Nonlinear Deformable Stringer of Finite Length is Glued. *Proceedings of NAS RA. Mechanics*, **50**:3–4 (1997), 17–26 (in Russian).

10. Melan E. *Ein Beitrag Zur Theorie geschweisster Verbindungen*. Ingenieur-Archiv, Bd.3, Heft 2 (1932), 123–129.
11. Shilov G.E. *Mathematical Analysis (Special Course)*. M. (1961), 442 p. (in Russian).
12. Kerobyan A.V. *To the Solution of the Problem for an Elastic Strip with Finite Number Elastic Finite Overlays Trough Adhesive Shear Layers. The Problems of Dynamic of Interaction of Deformable Media*. Proc. of IX Inter. Conf. Yer. (2018), 186–190 (in Russian).

Ա. Վ. ՔԵՐՈԲՅԱՆ

ՎԵՐՋԱՎՈՐ ԹՎՈՎ ՎԵՐՋԱՎՈՐ ՎԵՐԱԴԻՐՆԵՐԻՅ ԿՊՉՈՒՆ ՍԱՆՔԻ ՇԵՐՏԵՐԻ ՄԻՋՈՑՈՎ ԲԵՌՆԱՎՈՐՈՒՄՆԵՐԻ ՓՈԽԱՆՑՈՒՄՆ ԱՌԱՉԳԱԿԱՆ ՇԵՐՏԻՆ

Դիտարկված է առաձգական անվերջ շերտի վերաբերյալ խնդիր, որն իր ազապ եզրի երկայնությամբ ուժեղացված է փարբեր առաձգական հասկություններով և փոքր հաստապտուհ հասկություններով, վերջավոր թվով վերջավոր երկարությամբ վերադիրներով: Առաձգական շերտի և վերադիրների միջև փոխազդեցությունն իրագործվում է միատեսակ կաշուն շերտերի միջոցով: Վերադիրները դեֆորմացիայի են ենթարկվում նրանց ծայրերում կիրառված հորիզոնական ուժերի ազդեցության փակ: Շերտի և վերադիրների միջև գործող անհայտ շոշափող լարումների որոշման խնդիրը հանգեցված է փարբեր միջակայքերում որոշված վերջավոր թվով անհայտ ֆունկցիաների նկատմամբ Ֆրեդհոլմի երկրորդ սեռի ինտեգրալ հավասարումների համակարգի լուծմանը: Ցույց է փրված, որ խնդրի բնութագրիչ պարամետրերի փոփոխության որոշակի փոփոխում, ինտեգրալային հավասարումների այս համակարգը Բանախի փարածության մեջ կարող է լուծվել հաջորդական մոտավորությունների եղանակով: Դիտարկված են մասնավոր դեպքեր և պարզաբանված է շոշափող լարումների բաշխման բնույթը և վարքը: