Physical and Mathematical Sciences

2013, № 3, p. 23–28

Mathematics

ON A PROPERTY OF GENERAL HAAR SYSTEM

A. Kh. KOBELYAN *

Chair of Higher Mathematics (Department of Physics) YSU, Armenia

In the paper we prove that for some type of general Haar systems (particularly for classical Haar system) and for any $\varepsilon > 0$ there exists a set $E \subset (0,1)^2, |E| > 1 - \varepsilon$, such that for every $f \in L^1(0,1)^2$ one can find a function $g \in L^1(0,1)^2$, which coincides with f on E and Fourier–Haar coefficients $\{c_{(i,k)}(g)\}_{i,k=1}^{\infty}$ are monotonic over all rays.

MSC2010: 42C10; 42C40.

Keywords: general Haar system, convergence, Fourier-Haar coefficients.

Introduction. In this paper we will consider the behavior of the Fourier–Haar coefficients. Let us recall the definition of the general Haar system.

First we take $t_0 = 0$, $t_1 = 1$, $A_1^{(1)} = \Delta_1 = (0, 1)$, $h_1(x) = \chi_{(0,1)}$, where χ_E is the characteristic function of the set *E*.

Then choose any point $t_2 \in (0,1) \setminus \{t_0,t_1\}$, and let $A_1^{(2)} = (0,t_2), A_2^{(2)} = (t_2,1),$ $\Delta_2 = (0,1), \Delta_2^+ = (0,t_2), \Delta_2^- = (t_2,1).$ Define $h_2(x)$ in following manner:

$$h_2(x) = \begin{cases} \frac{1}{2|\Delta_2^+|}, & \text{if } x \in \Delta_2^+, \\ -\frac{1}{2|\Delta_2^-|}, & \text{if } x \in \Delta_2^-. \end{cases}$$

where |A| is the Lebesgue measure of the set A.

In the general case, let the points $t_0, t_1, ..., t_n$ be already chosen and let $A_1^{(n)}, A_2^{(n)}, ..., A_n^{(n)}$ be the partition intervals, enumerated from the left to the right, obtained from (0, 1) by removing points $\{t_k\}_{k=1}^n$. Choose any point t_{n+1} from $(0,1) \setminus \{t_0,t_1,...,t_n\}$. Then there exists an interval $A_k^{(n)} = (a,b)$ containing the point t_{n+1} . Denote $\Delta_{n+1} = (a,b), \Delta_{n+1}^+ = (a,t_{n+1}), \Delta_{n+1}^- = (t_{n+1},b)$ and

$$h_{n+1}(x) = \begin{cases} \frac{1}{2|\Delta_{n+1}^+|}, & \text{if } x \in \Delta_{n+1}^+, \\ -\frac{1}{2|\Delta_{n+1}^-|}, & \text{if } x \in \Delta_{n+1}^-, \\ 0 & \text{otherwise.} \end{cases}$$

^{*} E-mail: a_kobelyan@ysu.am

Note that the value of Haar functions at the points of discontinuity is not essential for the present paper. The only requirement to the points t_n is that the set $\mathcal{T} = \left\{t_k\right\}_{k=0}^{\infty}$ to be dense in [0, 1], i.e.

$$\lim_{k \to +\infty} \max_{1 \le k \le n} \left| A_k^{(n)} \right| = 0. \tag{1}$$

The function system $\mathcal{H} = \mathcal{H}_{\mathcal{T}} = \{h_n\}_{n=1}^{\infty}$ is the normalized in $L^1(0,1)$ general Haar system corresponding to the partition \mathcal{T} . For each \mathcal{T} (dense in [0,1]), the corresponding Haar system \mathcal{H} is a complete orthogonal system in $L^2[0, 1]$. There are many papers devoted to the general Haar system, see, e.g., [1,2].

The general Haar system is called an *M* type system, if for each $m \in \mathbb{N}$ there exists an n > m such that $t_{n+k} \in A_k^{(n)}$, k = 1, 2, ..., n and

$$\left|A_{1}^{(2n)}\right| \ge \left|A_{2}^{(2n)}\right| \ge \dots \ge \left|A_{2n}^{(2n)}\right|.$$
 (2)

For

$$\mathcal{T} = \left\{ 0, 1, \frac{1}{2}, \frac{1}{4}, \frac{3}{4}, \frac{1}{8}, \frac{3}{8}, \frac{5}{8}, \frac{7}{8}, \dots \right\},\,$$

we get the classical Haar system. Note that the classical Haar system is of M type. Let $\mathcal{T}_1, \mathcal{T}_2$ be dense sequences of points in [0,1]. Consider the system $\mathcal{H}_{(\mathcal{T}_1, \mathcal{T}_2)} = \{h_{\mathbf{n}} : \mathbf{n} \in \mathbb{N}^2\}$, where $\mathbf{n} = (n_1, n_2), h_{\mathbf{n}}(x, y) = h_{n_1}^1(x)h_{n_2}^2(y)$ with $h_{n_1}^1 \in \mathcal{H}_{\mathcal{T}_1}, h_{n_2}^2 \in \mathcal{H}_{\mathcal{T}_2}$.

We will say that $\mathcal{H}_{(\mathcal{I}_1,\mathcal{I}_2)}$ is an of M type general Haar system, if $\mathcal{H}_{\mathcal{I}_1}$ and $\mathcal{H}_{\mathcal{I}_2}$ are M type general Haar systems. Note that the Fourier-Haar coefficients $c_n(f,\mathcal{H}_{\mathcal{I}}), c_n(f,\mathcal{H}_{(\mathcal{I}_1,\mathcal{I}_2)})$ are determined by formulas

$$c_k(f, \mathcal{H}_{\mathfrak{T}}) = \frac{1}{||h_k||_{L^2}} \int_0^1 f(t)h_k(t)dt,$$

$$c_{(i,k)}(f, \mathcal{H}_{(\mathfrak{T}_1, \mathfrak{T}_2)}) = \frac{1}{||h_i^1||_{L^2}||h_k^2||_{L^2}} \int_{(0,1)^2} f(x, y)h_i^1(x)h_k^2(y)dxdy.$$

The spectrum of f(x,y) (denoted by <u>spec</u>(f)) is the support of $c_n(f)$, i.e. the index set where $c_n(f)$ is non-zero:

$$spec(f) = \{\mathbf{n} = (n_1, n_2), c_{\mathbf{n}}(f) \neq 0\}.$$

By ||f|| we will denote the L^1 -norm of f. We will say that the sequence $\{c_{(i,k)}(f)\}_{i,k=1}^{\infty}$ is monotonic over all rays, if

$$|c_{(i_1,k_1)}| \ge |c_{(i_2,k_2)}|$$
 for all $i_1 \ge i_2, k_1 \ge k_2$ for which $c_{(i_1,k_1)} \ne 0$.

The main result of the present paper is the following:

Theorem. For $\forall M$ type Haar system $\mathcal{H}_{(\mathcal{T}_1,\mathcal{T}_2)}$, and $\forall \varepsilon > 0$, there exist a set $E \subset (0,1)^2$, $|E| > 1 - \varepsilon$ such that for every function $f \in L^1(0,1)^2$ there exists a function $g \in L^1(0,1)^2$, which coincides with f on E and the Fourier–Haar coefficients $\{c_{(i,k)}(g)\}_{i,k=1}^{\infty}$ are monotonic over all rays.

Remark. This result is new for both M type general Haar system and the classical Haar system. Interesting results in this direction were obtained by many mathematicians [3–7].

Auxiliary Lemmas. Let T_1 , T_2 be two sequences of points dense in [0,1]. In the rest of the paper we will assume that the *M* type general Haar system $\mathcal{H}_{(\mathcal{T}_1,\mathcal{T}_2)}$ is fixed.

Let $A_1^{(1,n)}, A_2^{(1,n)}, \dots, A_n^{(1,n)}$ $\left(A_1^{(2,n)}, A_2^{(2,n)}, \dots, A_n^{(2,n)}\right)$ be the corresponding parti-

tion intervals for $\mathcal{T}_1 = \{t_k^1\}_{k=0}^{\infty}$ ($\mathcal{T}_2 = \{t_k^2\}_{k=0}^{\infty}$) (2). *Lemma 1*. For any $N_0 \in \mathbb{N}$, $0 < \varepsilon < 1$, $\delta > 0$, $L \neq 0$ and each set $\Delta \in \{A_k^{(n)}\}$ there exist a polynomial $Q(x) = \sum_{k=N_0}^N a_k h_k(x)$ in the *M* type general Haar system $\mathcal{H}_{\mathcal{T}}$ and a subset $E \subset \Delta$, satisfying the following conditions:

- 1. $\delta > |a_k|, k = N_0, N_0 + 1, \dots, N;$ 2. $|E| > (1-\varepsilon)|\Delta|; \quad ||Q|| \leq 2|L||\Delta|;$ 3. $Q(x) = \begin{cases} L, & x \in E, \\ 0, & x \notin \Delta; \end{cases}$
- 4. non-zero coefficients $\{a_k\}_{k \in spec(O)}$ are monotonically decreasing.

Proof. The proof can be done in the same way as the Lemma 2.2 of paper [8], keeping in mind the definition of M type general Haar system (2).

Lemma 2. For any $N_0 \in \mathbb{N}$, $\delta > 0$, $0 < \varepsilon < 1$, $L \neq 0$ and each set $\Delta = \Delta_1 \times \Delta_2 \subset (0,1)^2$, $\Delta_1 \in \left\{A_k^{(1,n)}\right\}$, $\Delta_2 \in \left\{A_k^{(2,n)}\right\}$ there exist a polynomial

$$Q(x,y) = \sum_{i,k=N_0}^{N} b_{(i,k)} h_i^1(x) h_k^2(y)$$

in the *M* type general Haar system $\mathcal{H}_{(\mathcal{T}_1,\mathcal{T}_2)}$ and a subset $E \subset \Delta$ such that:

1. $\delta > |b_{(i,k)}|; i,k = N_0, N_0 + 1, \dots, N;$ 2. $|E| > (1 - \varepsilon)|\Delta|;$ $||Q|| \le 4|L||\Delta|;$ 3. $Q(x,y) = \begin{cases} L, \text{ if } (x,y) \in E, \\ 0, \text{ if } (x,y) \notin \Delta; \end{cases}$ 4. the sequence $\left\{b_{(i,k)}\right\}_{i,k=N_0}^N$ is monotonic over all rays.

Proof. By applying Lemma 1 for L, Δ^1 and 1, Δ^2 we will find some sets E^1 , E^2 and polynomials $Q^1(x) = \sum_{i=N_0}^N a_i^1 h_i^1(x), Q^2(y) = \sum_{k=N_0}^N a_k^2 h_k^2(y)$ satisfying

$$\begin{split} \delta > |a_i^1|, \ 1 > |a_k^2|; \ i,k = N_0, \ N_0 + 1, \dots, N, \\ |E^1| > \left(1 - \frac{\varepsilon}{2}\right) |\Delta^1|; \ |E^2| > \left(1 - \frac{\varepsilon}{2}\right) |\Delta^2|; \\ ||Q^1|| \le 2|L||\Delta^1|; \ ||Q^2|| \le 2|\Delta^2|; \end{split}$$
(4)

$$Q^{1}(x) = \begin{cases} L, & \text{if } x \in E^{1}, \\ 0, & \text{if } x \notin \Delta^{1}; \end{cases} \quad Q^{2}(y) = \begin{cases} 1, & \text{if } y \in E^{2}, \\ 0, & \text{if } y \notin \Delta^{2}, \end{cases}$$
(5)

non-zero coefficients $\{a_i^1\}_{i \in \underline{spec}(Q^1)}, \{a_k^2\}_{k \in \underline{spec}(Q^2)}$ are monotonically decreasing. We define

$$Q(x,y) = Q^{1}(x)Q^{2}(y), E = E^{1} \times E^{2}.$$
(6)

Then it is easy to see that Q and E will satisfy to the conditions of Lemma 2.

Lemma 3. Let the numbers $N_0 > 1$, $\varepsilon > 0$, $\delta_1 > 0$, *M* type general Haar system $\mathcal{H}_{(\mathfrak{I}_1,\mathfrak{I}_2)}$ and the polynomial $f(x,y) = \sum_{r=1}^{R} L_r \chi_{\Delta_r}$ be given, where $\{\Delta_r\}_{r=1}^{R}$ are disjoint sets of the form $\Delta_r = \Delta_r^1 \times \Delta_r^2$. Then there exist a set $G \subset (0,1)^2$ and a polynomial $Q(x,y) = \sum_{i,k=N_0}^{N} a_{(i,k)} h_i^1(x) h_k^2(y)$ in the system $\mathcal{H}_{(\mathfrak{I}_1,\mathfrak{I}_2)}$, such that:

- 1. $\delta > |a_{(i,k)}|; i,k = N_0, N_0 + 1, \dots, N;$
- 2. $|G| > (1 \varepsilon); ||Q|| \le 4||f||;$
- 3. Q(x,y) = f(x,y) for all $(x,y) \in G$;
- 4. the sequence $\left\{a_{(i,k)}\right\}_{i,k=N_0}^N$ is monotonic over all rays.

Proof. By successively applying Lemma 2, we can find some sets $E_r \subset \Delta_r$ and polynomials

$$Q_r(x,y) = \sum_{i,k=N_{r-1}}^{N_r-1} b_{(i,k)}^r h_i^1(x) h_k^2(y),$$

satisfying

$$\delta_{r} > |b_{(i,k)}^{r}|; \ i,k = N_{r-1}, \dots, N_{r}; \ \delta_{r+1} = \min_{i,k,b_{(i,k)}^{r} \neq 0} |b_{(i,k)}^{r}|, \tag{7}$$

$$|E_r| > (1-\varepsilon)|\Delta_r|; \qquad ||Q_r|| \le 4|L_r||\Delta_r|, \tag{8}$$

$$Q_r(x,y) = \begin{cases} L_r, & \text{if } (x,y) \in E_r, \\ 0, & \text{if } (x,y) \notin \Delta_r, \end{cases}$$
(9)

the sequence $\left\{b_{(i,k)}^{r}\right\}_{i,k=N_{r-1}}^{N_r}$ is monotonic over all rays (for fixed *r*). We define the set *G* and the polynomial Q(x, y) in the following manner:

$$G = \bigcup_{r=1}^{R} E_r, \qquad Q(x, y) = \sum_{r=1}^{R} Q_r = \sum_{i,k=N_0}^{N} a_{(i,k)} h_i^1(x) h_k^2(y).$$

It is easy to see that set G and the polynomial Q(x,y) satisfy to the conditions of Lemma 3.

Proof of the Theorem. Let $\{f_r\}_{r=1}^{\infty}$ be the sequence of all polynomials with rational coefficients in *M* type general Haar system $\mathcal{H}_{(\mathcal{T}_1,\mathcal{T}_2)}$.

Successively applying Lemma 3, we will obtain sets $G_r \subset (0,1)^2$ and polynomials

$$Q_r(x,y) = \sum_{i,k=N_{r-1}}^{N_r-1} a_{(i,k)}^r h_i^1(x) h_k^2(y), N_0 = 1,$$

satisfying

$$\delta_r > \left| a_{i,k}^r \right|; \ i,k = N_{r-1}, \dots, N_r, \ \delta_{r+1} = \min_{i,k,a_{(i,k)}^r \neq 0} \left| a_{(i,k)}^r \right|; \ \delta_1 = 1, \tag{10}$$

$$|G_r| > \left(1 - \frac{\varepsilon}{2^r}\right); \quad ||Q_r|| \le 4||f_r||, \tag{11}$$

$$Q_r(x,y) = f_r(x,y) \text{ for all } (x,y) \in G_r$$
(12)

the sequence

$$\left\{a_{(i,k)}^{r}\right\}_{i,k=N_{r-1}}^{N_{r-1}}$$
(13)

is monotonic over all rays.

We denote

$$E = \bigcap_{r=1}^{\infty} G_r.$$
 (14)

From (11) we have that $|E| > 1 - \varepsilon$.

Let f(x,y) be an arbitrary element of $L^1(0,1)^2$. It is easy to see that one can choose a subsequence $\{f_{r_n}\}_{n=1}^{\infty}$ of the sequence $\{f_r\}_{r=1}^{\infty}$ such that

$$\lim_{N \to \infty} \left\| \sum_{n=1}^{N} f_{r_n} - f \right\| = 0, \qquad ||f_{r_n}|| \le 2^{-2n}, \ n \ge 2.$$
(15)

Define the function g(x, y) as follows;

$$g(x,y) = \sum_{n=1}^{\infty} Q_{r_n}(x,y).$$

From (11)–(15) we get that $g \in L^1(0,1)^2$,

$$g(x,y) = f(x,y)$$
 for $(x,y) \in E$

and

$$c_{(i,k)}(g) = \frac{1}{||h_i^1||_{L^2}||h_k^2||_{L^2}} \int_{(0,1)^2} g(x,y)h_i^1(x)h_k^2(y)dxdy = a_{(i,k)}^r$$

where $(i,k) \in [N_{r-1},N_r)^2$. Then (10) and (13) imply that $\{c_{(i,k)}(g)\}_{i,k=1}^{\infty}$ is monotonic over all rays.

Received 23.04.2013

$\mathbf{R} \to \mathbf{F} \to \mathbf{R} \to \mathbf{N} \to \mathbf{C} \to \mathbf{S}$

 Kamont A. General Haar System and Greedy Approximation. // Studia Math., 2001, v. 145, № 2, p. 165–184.

- Gogyan S.L. On Greedy Algorithm in L¹(0,1) by Regular Haar System. // Izv. NAN RA, Matem., 2011, v. 46, № 1, p. 3–16 (in Russian).
- 3. Grigoryan M.G., Gogyan S.L. Non Linear Approximation by Haar System and Modification of Functions. // Analysis Mathem., 2006, v. 32, p. 49–80.
- Tao T. On the Almost Everywhere Convergence of Wavelet Summation Methods. // Applied and Computational Harmonic Analysis, 1996, v. 3, № 4, p. 384–387.
- 5. Gevorgyan G.G., Stepanyan A.A. On the Almost Everywhere Divergence of a Summation Method for Wavelet Expansions. // Izv. NAN RA. Matem., 2004, v. 39, № 2, p. 27–32 (in Russian).
- 6. Dilworth S.J., Kutzarova D., Wojtaszczyk P. On Approximate *l*₁ Systems in Banach Spaces. // Journal of Approximation Theory, 2002, v. 114, p. 214–241.
- 7. **Temlyakov V.N.** The Best *m*-Term Approximation and Greedy Algorithms. // Advances in Comp. Mathem., 1998, v. 8, № 3, p. 249–265.
- Kobelyan A.Kh. Convergence of Greedy Algorithm in L¹ with Respect to General Haar System. // Izv. NAN RA. Matem., 2012, v. 47, № 6, p. 53–70 (in Russian).